

Fundamental Mathematics for Robotics Homework Set #06-2, Dr.T

- [1] Answer the following questions using the same matrices given in Problem [3], Homework Set #06-1, which are:

$$A = \begin{bmatrix} -3 & -2 \\ 7 & 5 \end{bmatrix}, B = \begin{bmatrix} -1 \\ 7 \end{bmatrix}, C = [2 \quad 1], D = [1]$$

- (a) Compute A^{-1}
 - (b) Find \vec{x} such that $A\vec{x} = B$
 - (c) Find \vec{x} such that $\vec{x}^T A = C$
 - (d) Can you compute $(BC)^{-1}$? How about $(CB)^{-1}$?
 - (e) (Extra) Compute $(xI - A)^{-1}$
 - (f) (Extra) Compute $C(xI - A)^{-1}B + D$
- [2] Find two 2×2 matrices with the following property:
- (a) $M^T = M, M \neq I$
 - (b) $M^T = -M, M \neq \Theta$
 - (c) $M^T = M^{-1}$
- [3] Show that for any square matrix M (2×2),
- (a) $Q \triangleq \frac{M+M^T}{2}$ is a symmetric matrix.
 - (b) $W \triangleq \frac{M-M^T}{2}$ is asymmetric matrix.
 - (c) $M = Q + W$
 - (d) (Extra) What is the implication of (c)?
- [4] In robotics, we often use a matrix $R(\theta) \triangleq \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix}$. Answer the following questions on this matrix.
- (a) Compute $\vec{y} = R(\theta)\vec{x}$, where $\vec{x}^T = [x_1 \quad x_2]$.
 - (b) Compute the norm $\|\vec{x}\|$.
 - (c) Compute the norm $\|\vec{y}\|$.
 - (d) Compute the inner product $\vec{x} \cdot \vec{y}$ (Note: $\langle \vec{x}, \vec{y} \rangle$ is also used for the inner product)
 - (e) Show that $\det R(\theta) = 1$ for any θ .
 - (f) Compute $R(\theta)^{-1}$.
 - (g) Show that $R(\theta)^T = R(\theta)^{-1}$.
 - (h) Show that $R(\theta)^{-1} = R(-\theta)$.
 - (i) (Extra) Find the angle ϕ between the two vectors \vec{x} and \vec{y} .
 - (j) (Extra) Show that the 1st column and the 2nd column of this matrix $R(\theta)$ are orthogonal (normal) regardless of the value of θ . (Hint: What happens to the inner product of two orthogonal vectors?)
- (Note: This matrix is called the rotation matrix.)

Fundamental Mathematics for Robotics
Extra Homework Set #06-Extra1, Dr.T

[1] Compute the norm of the following vector:

(a) $\vec{x} = [3 \quad -2]^T$

(b) $\vec{y} = [1 \quad -3]^T$

(c) $\vec{z} = [4 \quad -2 \quad 3]^T$

(d) $\vec{w} = [2 \quad -2 \quad -3]^T$

(e) $\vec{v} = [-1 \quad 4 \quad 2 \quad -3]^T$

(f) $\vec{u} = [3 \quad -1 \quad 4 \quad -2]^T$

[2] Compute the inner products of the vectors in Problem [1] for all possible combinations.

[3] Compute the matrix products of pairs of matrices among the following matrices when possible.

$$L = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}, \quad M = \begin{bmatrix} 2 & -2 & 1 \\ 3 & 1 & -2 \end{bmatrix}, \quad N = \begin{bmatrix} -2 & 1 \\ -1 & -2 \\ 1 & 1 \end{bmatrix} \quad \text{and} \quad P = \begin{bmatrix} -3 & 1 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

[4] Compute the matrix-vector products of the vectors in Problem [1] and the matrices in Problem [3] for all possible combinations.

[5] Compute the determinants of the matrices in Problem [3] if possible.

[6] Compute the inverse matrices of the matrices in Problem [3] if possible.

[7] (Extra) Now, let us consider powers of a matrix, namely, M^n for a matrix M . Discuss how we should define it and what the condition(s) should be.

[8] (Extra) If $x^2 = 0$ for a scalar x , then $x = 0$. It is not true for a matrix M , i.e., even if $M^2 = \Theta$ M may not be Θ . Here Θ is a zero matrix whose elements are all zero. Give an example of non-zero 2x2 matrix M for which $M^2 = \Theta$.

Fundamental Mathematics for Robotics
Extra Homework Set #06-Extra2, Dr.T

- [1] Compute the norm of the given vectors. Also, compute inner products of all possible combinations.

$$\vec{x} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}, \quad \vec{y} = \begin{bmatrix} 3 \\ -2 \end{bmatrix}, \quad \vec{z} = \begin{bmatrix} -2 \\ 4 \end{bmatrix}, \quad \vec{w} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad \vec{v} = \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix} \quad \text{and} \quad \vec{u} = \begin{bmatrix} -7 \\ 2 \\ 1 \end{bmatrix}$$

- [2] Compute the inverse matrix if you can.

$$\begin{aligned} \text{(a)} \quad A_1 &= \begin{bmatrix} 1 & 3 \\ 4 & 2 \end{bmatrix}, & \text{(b)} \quad A_2 &= \begin{bmatrix} -4 & 1 \\ -1 & -2 \end{bmatrix}, & \text{(c)} \quad A_3 &= \begin{bmatrix} 3 & 2 \\ -6 & -4 \end{bmatrix}, & \text{(d)} \quad A_4 &= \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \\ \text{(e) (Extra)} \quad A_5 &= \begin{bmatrix} 2 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & -3 \end{bmatrix}, & \text{(f) (Extra)} \quad A_6 &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -11 & -6 \end{bmatrix} \end{aligned}$$

- [3] Given a 2x2 matrix A, $A = \begin{bmatrix} -3 & -4 \\ 5 & 6 \end{bmatrix}$, answer the following questions:

- (a) Compute A^2
- (b) Compute $3A - 2I$
- (c) Compute A^{-1}
- (d) Compute $-\frac{1}{2}A + \frac{3}{2}I$
- (e) (Extra) Compute A^{-2} using the result of (a), namely, $A^{-2} = (A^2)^{-1}$
- (f) (Extra) Compute A^{-2} using the result of (c), namely, $A^{-2} = (A^{-1})^2$
- (g) Compute $-\frac{3}{4}A + \frac{7}{4}I$
- (h) (Extra) Can you find α and β such that $A^3 = \alpha A + \beta I$